



5-axis vice TeleSense, Type: 125CONNECT



Order data

Order number	361270 125CONNECT
GTIN	4250364404068
Item class	34H

Description

Version:

- Optimum for use on 5-axis machining centres.
- Constant clamping force thanks to the low-maintenance telescopic spindle. Interference contours remain unchanged.
- Jaws can be changed without using tools thanks to quick release fastener.
- Supplied as standard with 25H6 M10 mounting holes for zero-point clamping system with 200 mm pitch.
- Clamping force 40 kN at 50 Nm linear.
- Maximum flexibility: Universal quick-change jaw for a wide variety of applications; thus reducing set-up time and requiring less force. Compatible with the mobile jaws of CentroGripp, T-Rex, NC8 and Titan 2 via the jaw adapter.
- It is possible to measure the clamping force with all compatible jaws thanks to the integral measuring unit (size 125CONNECT) in the spindle. Transmission range up to 20 m. Quick and easy change of the battery. Operating temperature between 10 °C and 40 °C. QR code on the nameplate for quick access to technical information, accessories, spare parts and service.
- Conventional clamping and gripping clamping with intelligent clamping force monitoring.
- Monitoring of the clamping force during clamping and machining by means of an integrated electronic measuring system. Display directly on a robust and splash-proof display and via wireless transmission to the end device (via Bluetooth® (BLE)).

Supplied with:

Hand crank, Torx T10 key, Quick Start Guide.

Optional extras:

Torque wrench No. 656050 size 120, hexagon bit socket No. 643229 size 10, top jaws No. 361275 – 361285, clamping claw No. 361289, clamping stud No. 360025 size 25M10 or 25M10/138; jaw adapter No. 361285, Gripp strip No. 361280, spindle extension No. 361287. Further accessories available on request.

Technical description

Height h	187 mm
Clamping force up to maximum	40 kN
Weight	39 kg
maximum torque	50 Nm
maximum clamping range	199 mm
Version	Zero-point clamping system
Type of product	Machine vice